

PUMA MX series

Multi-Tasking Turning Center



PUMA MX series

The integration of machining center and turning center gives you unmatched flexibility in a wide variety of part configurations. From simple turning and milling, to complex multi-axis simultaneous machining, all operations can be completed in one machine. Off-center machining with the Y-axis and milling of angled surfaces with the B-axis greatly increases the range of machine applications.



Multi-Tasking Turning Center



Machine Construction

The milling spindle(s) and the lower turret can be coordinated to enable machining at the left or right spindle.



PUMA MX series

Robust Design PUMA MX2100

Stable base for supporting multi-machining

The heavily ribbed torque tube design prevents twisting and deformation. All guideways are wide wrap-around rectangular type for unsurpassed long-term rigidity and accuracy.

	Guideway span		
	MX2100		
X1-axis	285 / 315 mm (11.2 / 12.4 inch)		
Z1-axis	540 / 473 mm (21.3 / 18.6 inch)		
Y-axis	435 mm (17.1 inch)		

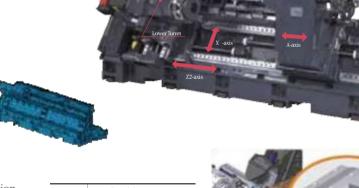
FEM

Finite Element Method (FEM) analysis results in superior machine stability.

Linear Motion Guide (Roller type)

All carriages are mounted on roller-type, linear motion guides to provide high accuracy and rigidity while reducing non-cutting time.

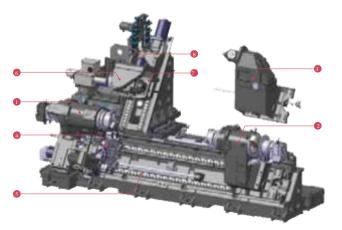
- -Zero clearance from preload → High permissible load
- Low friction & wear (LM μ = 0.002~0.003)
- Simple maintenance over the long haul



	Rapid traverse
X1-axis	36 m/min (1417.3 ipm)
Z1-axis	36 m/min (1417.3 ipm)
Y-axis	26 m/min (1023.6 ipm)

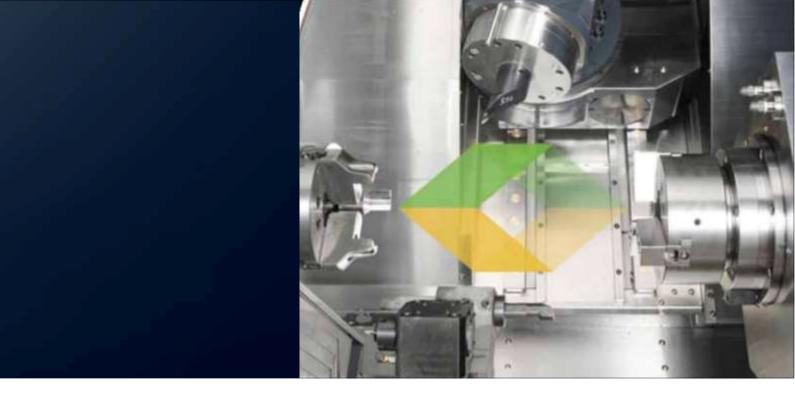


LMG (Roller type)



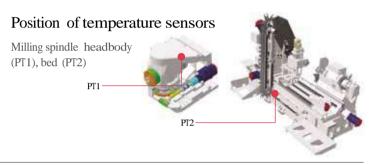
PUMA MX1600

	PUMA MX1600	PUMA MX1600S	PUMA MX1600T	PUMA MX1600ST
Left spindle (Mill-turn): 175mm (6") chuck	•	•	•	•
Right spindle (Mill-turn): 175mm (6") chuck	×	•	×	•
3 Tail stock : Servo driven type	•	×	•	×
Lower turret: 16-station 6000 r/min rotary tool	×	×	•	•
6 Roller guide ways for all axes	•	•	•	•
Milling spindle: 12000 r/min, Capto C5	•	•	•	•
7 B-axis: Roller gear cam	•	•	•	•
ATC & Magazine: 40 ea, Servo driven	•	•	•	•



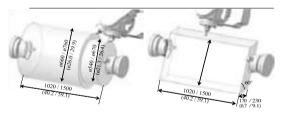
Thermal compensation system

Milling spindle thermal growth can be compensated for spindle axis direction only. Effectively removes positional deviation of spindle nose due to changing rotational speed.



Axis Features

Max. working diameter, length (MX 2100 / MX 2600, 3100)

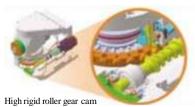


Axis t	ravel	Uni	it: mm (inch)
	PUMA MX 2100/2100L	PUMA MX2600/3100	MX1600
X1-axis	565 (22.2)	630 (24.8)	450 (332.1)
X2-axis	187 (7.4)	220 (8.7)	165 (121.8)
Z1-axis	1050/1550 (41.3 / 61.0)	1585 (62.4)	935 (690.0)
Z2-axis	1050/1550 (41.3 / 61.0)	1515 (59.7)	925 (682.7)

Rapi	d travel	Unit:	m/min (ipm)
	PUMA MX2100ST	PUMA MX2600ST	MX1600
X1-axi	s 36 (1417.3)	36 (1417.3)	36 (1417.3)
X2-axi	s 24 (944.9)	24 (944.9)	24 (944.9)
Z1-axi	s 36 (1417.3)	36 (1417.3)	36 (1417.3)
Z2-axi	s 36 (1417.3)	36(1417.3)	36 (1417.3)
A-axis	30 (1181.1)	30 (1181.1)	
C-axis	400 (15748.0) r/min	400 (15748.0) r/min	

B-Axis with Virtual Y-Axis





B-axis rotating range std.



Precise indexing control of B-axis makes milling jobs on inclined plane possible.

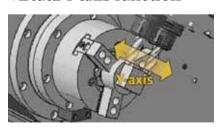
- 5° indexing (by coupling clamp)
- Contouring control in 0.001° increment

B-axis rotation range $\pm 120^{\circ}$ B-axis indexing time 2 s (90°)

Precision control B-axis movement

The angular position of the B-axis is controlled using precision ground roller gear cam and a highly accurate servo motor.

Virtual Y-axis function



A rigid, double-slide Y-axis construction withstands cutting forces generated during heavy-duty turning and milling.

Y-axis stroke 170 mm (6.7 inch) / 230 mm (9.1 inch) $[\pm 85 \text{ mm } (3.4 \text{ inch}) / \pm 115 \text{ mm } (4.5 \text{ inch})]$

Y-axis rapid traverse 26 m/min (1023.6 ipm)

Main Spindle

The Perfect Design for Built-in Motor-Driven Spindles.

PUMA MX series

Main Spindle

Both spindles, left and right, are engineered to minimize the loss of precision through thermal distortion, and to ensure superior performance in applications ranging from heavy-duty cutting at high power and low speed, to fine finishing at high speed.

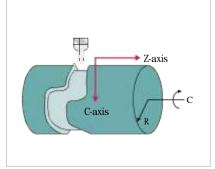
	Max. spindle speed	Motor (30 min)
PUMA MX1600	6000 r/min	15 kW (20.1 Hp)
PUMA MX2100	5000 r/min	22 kW (29.5 Hp)
PUMA MX2600	4000 r/min	26 kW (34.9 Hp)
PUMA MX3100	3000 r/min	30 kW (40.2 Hp)

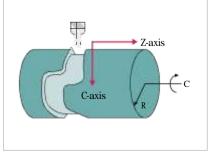


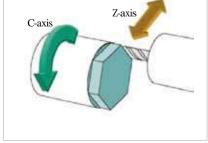
Perfect C-axis control of both spindles

C1, C2-axis index 360° [in 0.001° increment]

	C1, C2-axis contouring torque
MX1600	208 N·m (153.5 ft·lb)
MX2100S [L/ST/LST]	318 N·m (125.5 ft·lb)
MX2600S/ST	700 N·m (516.6 ft·lb)
MX3100S	1203 N·m (887.8 ft·lb)







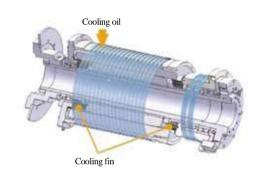
C&Z-axis cylindrical interpolation

C&X-axis polar interpolation



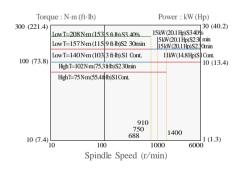
Oil cooling unit for left & right spindles

Both the left and right spindles employ an integral cooling system that circulates coolants through the entire spindle structure. This eliminates thermal distortion in all applications from heavy-duty cutting at high power and low speeds to fine and finish cutting at high speed.



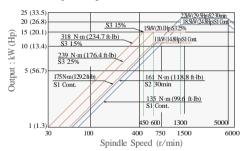
Spindle power-torque diagram

PUMA MX1600



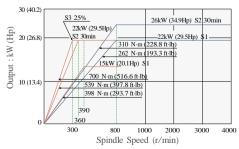
PUMA MX 2100 series (Left & right spindle)

- Spindle motor power : 22 kW (29.5 Hp)
- Max. Spindle speed: 5000 r/min



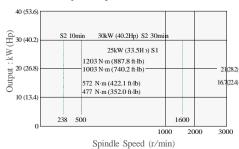
PUMA MX 2600 series (Left & right spindle)

- Spindle motor power : 26 kW (34.9 Hp)
- Max. Spindle speed: 4000 r/min



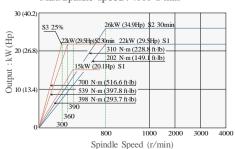
PUMA MX 3100 series (Left spindle)

- Spindle motor power : 30 kW (40.2 Hp)
- Max. Spindle speed: 3000 r/min



PUMA MX 3100 series (Right spindle)

- Spindle motor power: 26 kW (34.9 Hp)
- Max. Spindle speed: 4000 r/min



Milling Spindle

Turning and Milling Perfectly Integrated.

PUMA MX series

Milling Spindle



Oil-based coolants circulate through the milling spindle, allowing perfect integration of turning and milling applications. An air-gap sensor confirms the clamping status of both tools and parts.

Max. spindle speed 12000 r/min

	Motor	Torque
PUMA MX1600	9 kW (12.1 Hp) [10 min]	49 N·m (36.2 ft·lb)
PUMA MX2100	18.5 kW (24.8 Hp) [10 min]	81 N·m (59.3 ft·lb)
PUMA MX2600/3100	22 kW (29.5 Hp) [15 min]	118 N·m (87.1 ft·lb)

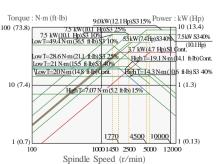


Dual Contact Tools (MX 1600 - CAPTO C5, MX2100/2600/3100 - CAPTO C6)

The 360° angular positioning of the milling spindle can accommodate multi insert turning tools that are equipped with two, three, or four inserts.

Milling spindle power-torque diagram

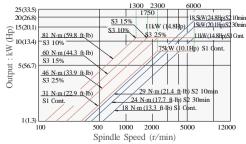
PUMA MX1600



PUMA MX2100 series

• Spindle motor power: 18.5 kW (24.8 Hp)

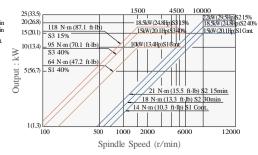
• Max. Spindle speed: 12000 r/min



PUMA MX2600/3100 series

• Spindle motor power: 22 kW (29.5 Hp)

• Max. Spindle speed: 12000 r/min





Tool Magazine with ATC



Automatic Tool Changer (ATC)

Advanced mechanisms significantly reduce non-cutting time.

	Tool change time
PUMA MX1600	2.1 s (T - T - T)
PUMA MX2100	2.0 s (T - T - T)
PUMA MX2600/3100	2.0 s (T - T - T)

Tool storage capacity

The ATC consists of a servo-driven tool magazine and change arm.

40 ea / 80 ea opt

Tool Magazine



Maximum tool size

	- L1	\Rightarrow
Α	Ţw	900
-	L	

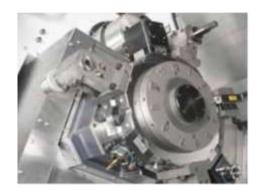
	May to all anoth []		Max. tool diameter [A]		Max. moment	
	Max. tool length [L]	Adjacent pots are empty	Continuous	Max. tool weight [W]	[W x L1]	
PUMA MX1600	200 mm (7.9 inch)	Ø 95 mm (3.7 inch)	Ø 70 mm (2.8 inch)	4 kg (8.8 lb)	3.9 N·m (2.9 ft·lb)	
PUMA MX2100	300 mm (11.8 inch)	Ø 120 mm (4.7 inch)	Ø 90 mm (3.5 inch)	8 kg (17.6 lb)	7.54 N·m (5.6 ft·lb)	
PUMA MX2600/3100	400 mm (15.8 inch)	Ø 130 mm (5.1 inch)	Ø 90 mm (3.5 inch)	10 kg (22.0 lb)	9.81 N·m (7.2 ft·lb)	

Lower Turret

Designed for High Accuracy

PUMA MX series

Lower Turret *1



The 12-station, heavy-duty lower turret features a large-diameter Curvic coupling with heavyduty design for maximum rigidity under tough cutting conditions. Turret rotation, acceleration and deceleration are controlled by a high-torque servo motor. Unclamp and rotation are virtually simultaneous. The fast index response keeps cycle times short.

Index time (1-station swivel) 0.2 s

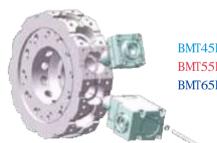
No. of tool station 12 ea (MX2100/2600/3100)

16 ea (MX1600)

*1 : on only T, ST type machine

Radial BMT45P (MX1600), BMT55P (MX2100) and the BMT65P (MX2600)

The turret accommodates BMT55P and BMT65P tooling in which the toolholders are mounted directly to the turret's periphery with 4 large bolts. This type of mounting system generates exceptionally high rigidity.



BMT45P (MX1600) BMT55P (MX2100) BMT65P (MX2600)

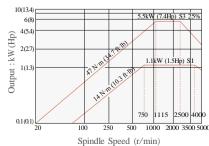
Rotary tool spindle power-torque diagram

PUMA MX1600

Torque: N·m (ft·lb) 50 (36.9) T=23.5 N·m (17.3 ft·lb) S3 25 % 10 (7.4) T=7 N·m (5.2 ft·lb) S1 Cont. 1 (0.7) 1 (0.7) Spindle Speed (r/min)

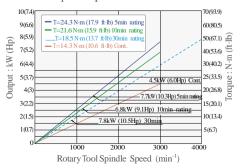
PUMA MX2100 series

- Spindle motor power: 5.5 kW (7.4 Hp)
- Max. Spindle speed: 5000 r/min



PUMA MX2600 series

- Spindle motor power: 7.8 kW (10.5 Hp)
- Max. Spindle speed: 4000 r/min





Servo Driven Tail Stock *1



The tail stock is driven by an AC servo motor and ball screw. Tail stocks thrust force can be controlled and adjusted by using the controls M-code function.

Programmable tail stock specifications

Model	Unit	MX1600	MX2100	MX2600 / 3100
Bore taper		MT#4	MT#4	MT#5
Travel	mm (inch)	935 (36.8)	1050 (41.3)	1550 (61.0)
Max. thrust force	N (lbs)	3500 (786.8)	7000 (1573.6)	10000 (22480.0)

Machining Capacity



Heavy duty cutting (MX2600)





Milling 1 (MX2600)

(Face	mil	ling





Milling 2 (MX2600)

(End milling)

Milling Spindle speed	Tool [6Z]	Cutting depth	Feedrate m/rev	Material removal rate cm³/min (in³/min)
380	Ø25 (1.0)	25 (1.0)	0.5	119 (46.9)



Milling 3 (MX2100)

(Drilling)

-	Milling Spindle speed	Tool [U-drill]	Feedrate	Material removal rate
	r/min	mm (inch)	m/rev	cm³/min(in³/min)
	2000	Ø40 (3.2) [6Z]	0.2	503 (9.7)

- Workpiece material, KS (JIS): SM45C (S45C), Carbon steel
- The cutting test results indicated above are obtained as an example through real test cutting.
- The results may not be obtained due to differences in cutting and environmental conditions during measurement.

^{*1:} The servo-driven tail stock with dead center (built in center) is standard on MX2100, 2600/3100 models, but not on those designated as S and ST models.

Application of Hybrid Motor Starter (Standard Specifications)

Innovative maintenance-free conditions have been realized compared with conventional motor-driven starters via the application of a hybrid motor starter that allows intellectual switching and simple cabling upon frequent operation of the coolant pump motor.



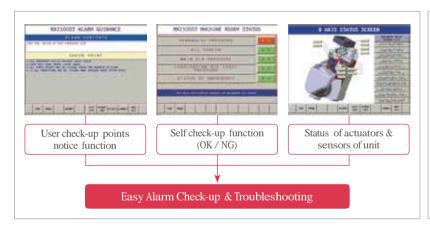
Hybrid motor starter that allows intellectual motor switching and simple cabling

The hybrid motor starter is capable of starting up the motor faster and more securely than competing motor starters.

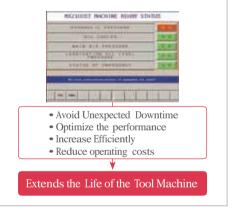
Hybrid switching technology, fitted with semiconductors for the supply of power, allows streamlined switching, thereby radically reducing the load on relay contacts and extending the lifecycle of the motor starter tenfold compared with conventional switch gear, and facilitates simple and efficient cabling design at the control and signal levels.

Easy Operation System

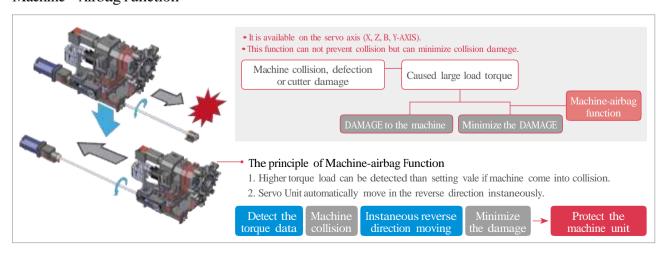
Alarm Guidance



Periodic maintenance function



Machine - Airbag Function



Various Optional Equipments







Oil mist collector

Oil skimmer

Servo driven steady rest (Automatic type)

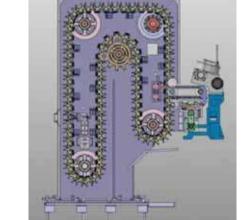




Air+Oil mist Misting device

Tool setter

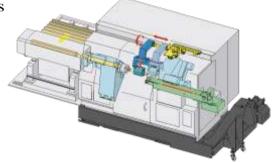
MQL (Minimum quantity lubrication)



Tool magazine 80 tools

Optional Equipments for Automation

- Bar feeder
- Parts unloader & Parts conveyor
- Work ejector

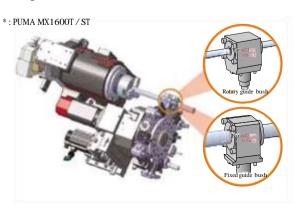


Guide bush* opt.

Combined MX technology with Swiss-turn function for biomedical complex shapes

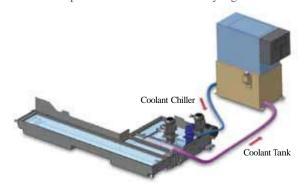
Rotary guide bush Below 21 mm (0.8 inch)

Fixed guide bush Below $22 \text{ mm} \sim 42 \text{ mm} (0.9 \text{ inch} \sim 1.7 \text{ inch})$



Coolant chiller opt

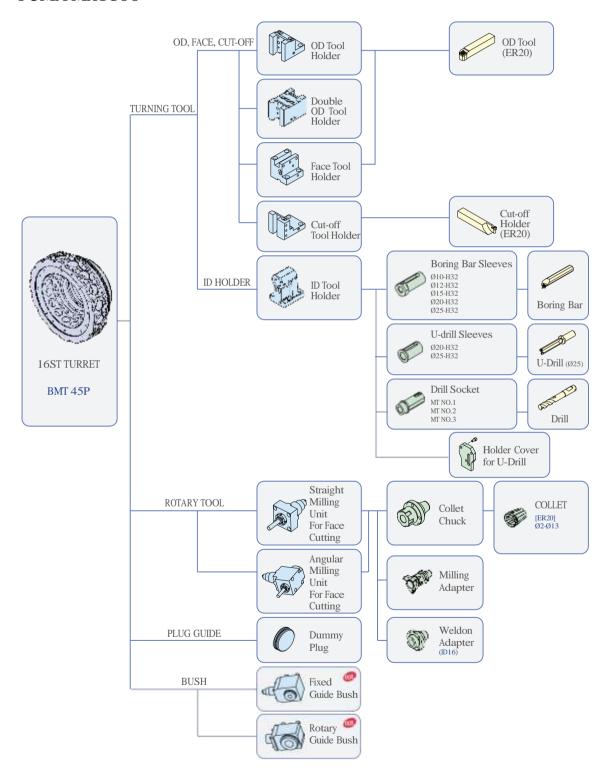
Thermal displacement and dimensional accuracy are greatly influenced by oil temperature in a machine. Coolant Temperature Control unit prevents the coolant from heating. Especially, when using oil-based coolant, the oil temperature can become extremely high.



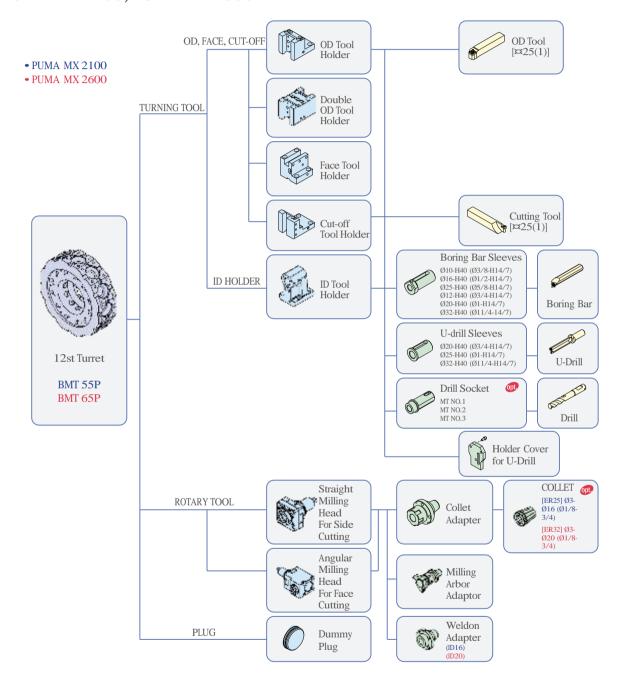
Tooling System

Unit: mm (inch)

PUMA MX1600



PUMA MX2100, PUMA MX2600



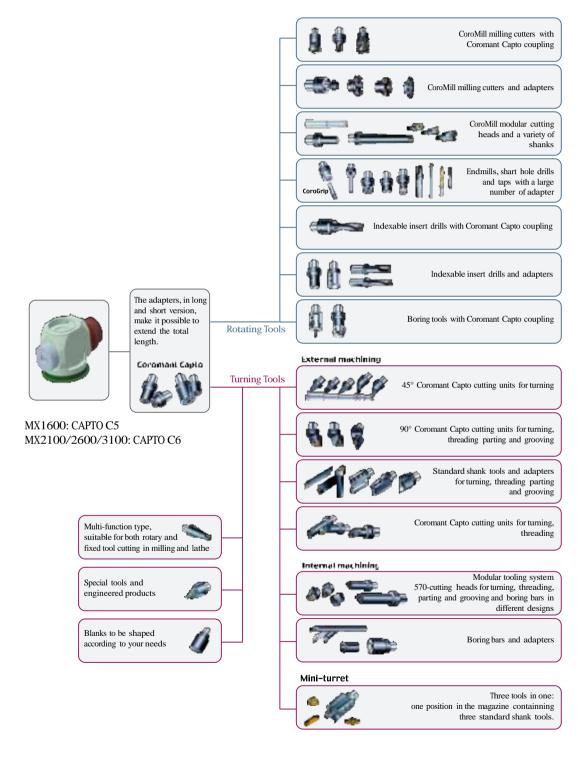
Note) Above tooling system is our recommendation.

Depending on export condition, the standard tooling packed with the machine can be different.

Tooling System

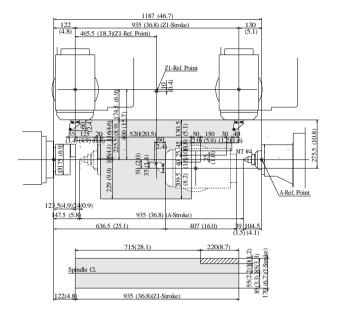
Unit: mm (inch)

Milling spindle

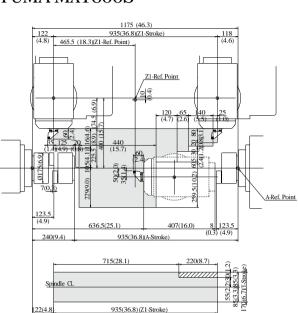


[•] All holders are not supplied. It is only reference for you.

PUMA MX1600

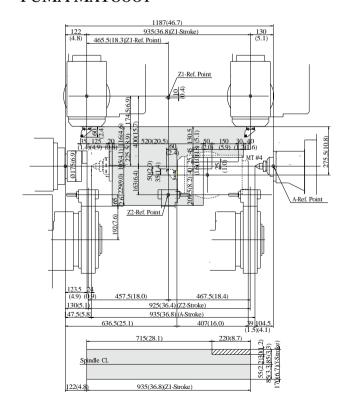


PUMA MX1600S

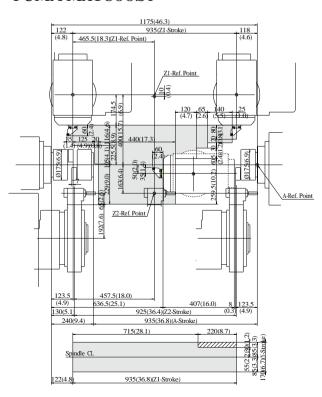


Unit: mm (inch)

PUMA MX1600T



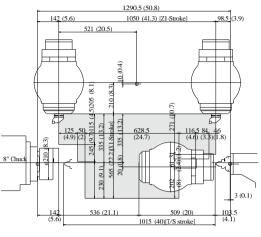
PUMA MX1600ST

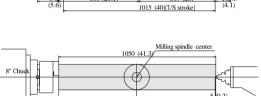


PUMA MX2100

PUMA MX2100S

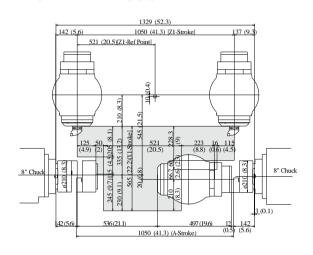
Unit: mm (inch)

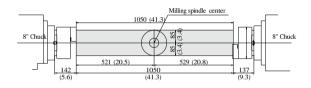




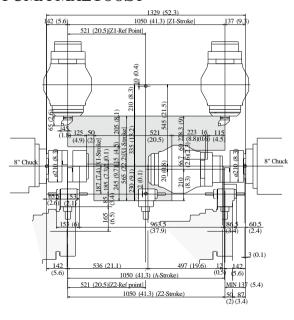
529 (20.8)

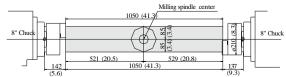
521 (20.5)



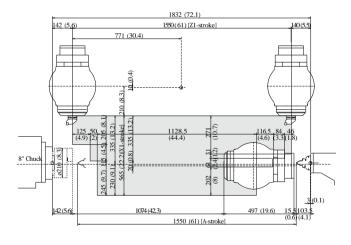


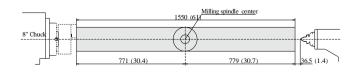
PUMA MX2100ST





PUMA MX2100L

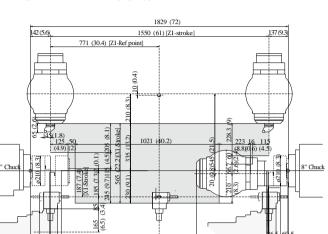




PUMA MX2100LS

1829 (72) 1550 (61) |Z1-stroke| 137 (9.3) 771 (30.4) |Z1-Ref point| 1829 (72) 1550 (61) |Z1-stroke| 137 (9.3) 137 (9.3) 137 (9.3) 137 (9.3) 137 (9.3) 137 (9.3) 137 (9.3) 137 (9.3) 137 (9.3) 137 (9.3) 137 (9.3) 138 (1.5) 139 (1.5) 139 (1.5) 142 (1.5) 150 (61) |A-stroke| 137 (9.3) 137 (9.3) 138 (1.5) 138 (1.5) 139 (1.5) 130 (1.5) 142 (1.5) 1550 (61) |A-stroke| 137 (1.5) 150

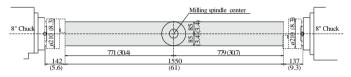
PUMA MX2100LST

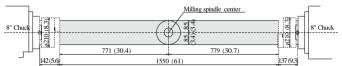


Unit: mm (inch)

MIN 137 (5.4)

50 87 (2)(3.4)





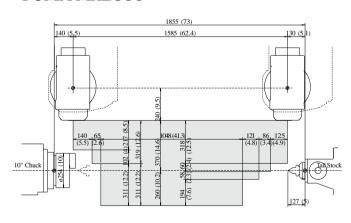
1550 (61) [A-stroke]

1550 (61) [Z2-stroke]

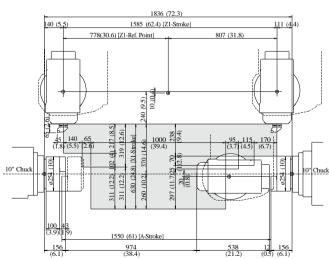
1036 (40.8)

771 (30.4) [Z2-Ref point]

PUMA MX2600

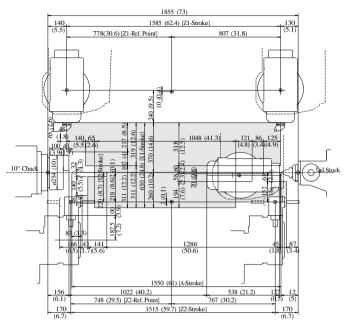


PUMA MX2600S

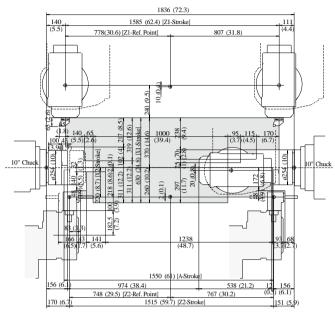


Unit: mm (inch)

PUMA MX2600T

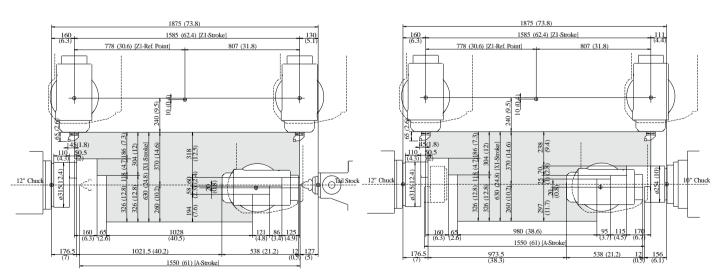


PUMA MX2600ST



PUMA MX3100

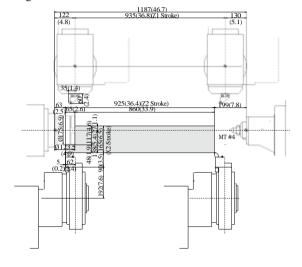
PUMA MX3100S



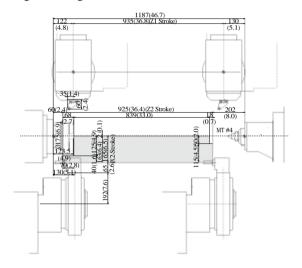
Unit: mm (inch)

PUMA MX1600T

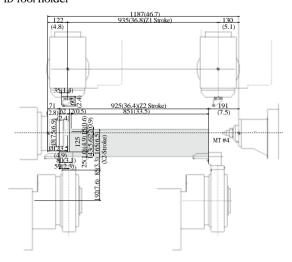
Single OD Tool holder



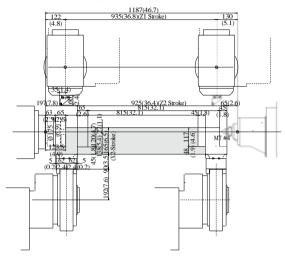
Angular milling head



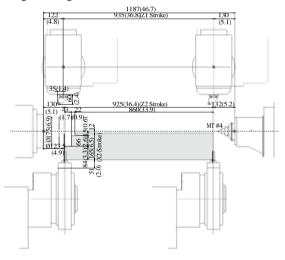
ID Tool holder



Double OD Tool holder



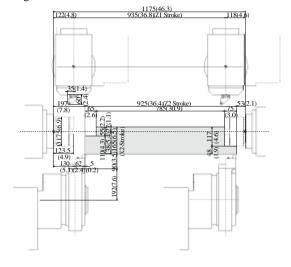
Straight milling head



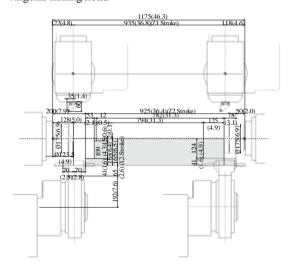
Unit: mm (inch)

PUMA MX1600ST

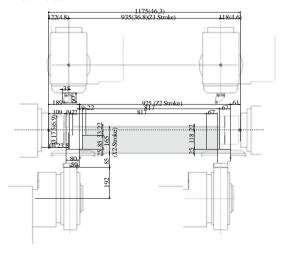
Single OD Tool holder



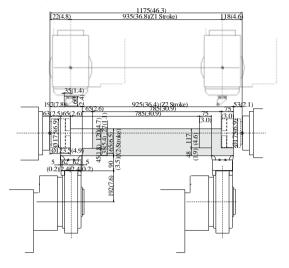
Angular milling head



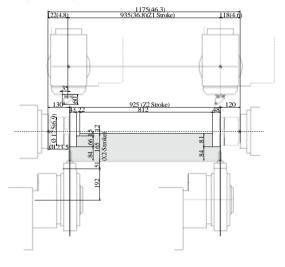
ID Tool holder



Double OD Tool holder



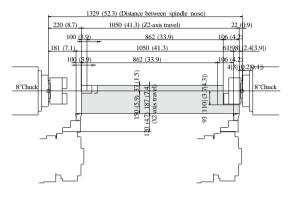
Straight milling head



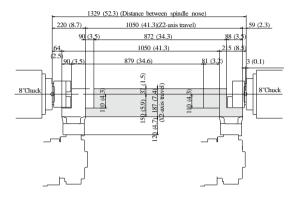
Unit: mm (inch)

PUMA MX2100ST / PUMA MX 2100T

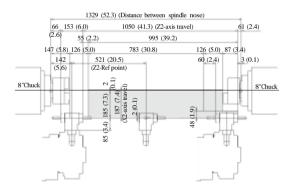
Single OD Tool holder



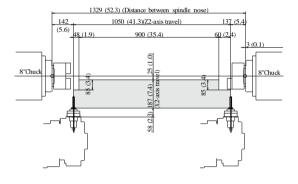
Double OD Tool holder



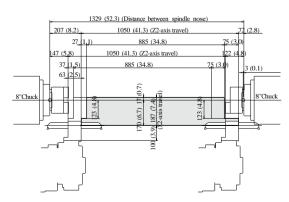
Angular milling head



Straight milling head



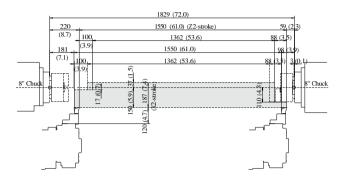
ID Tool holder



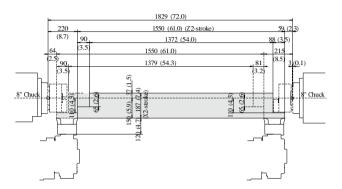
Unit: mm (inch)

PUMA MX2100LST

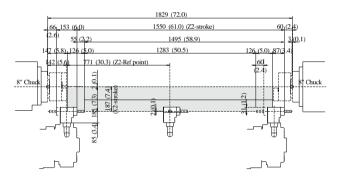
Single OD Tool holder



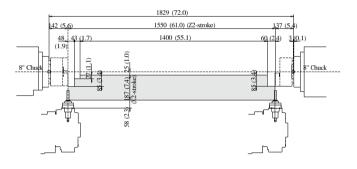
Double OD Tool holder



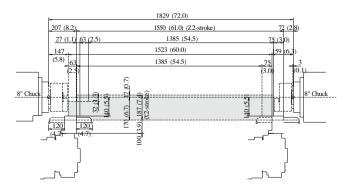
Milling (Angle) head



Milling (ST) head



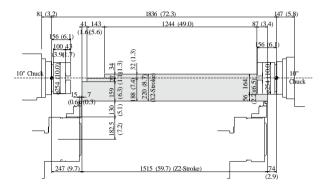
ID Tool holder



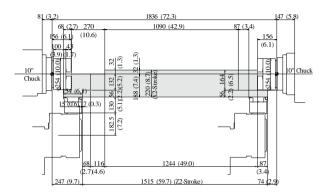
Unit: mm (inch)

PUMA MX2600ST / PUMA MX 2600T

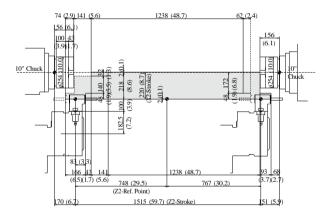
Single OD Tool holder



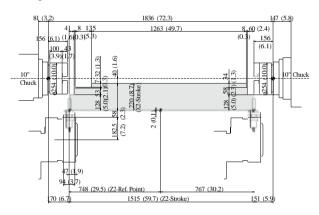
Double OD Tool holder



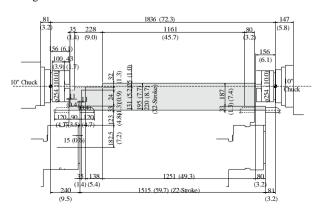
Milling (Angle) head



Milling (ST) head



Boring Bar holder

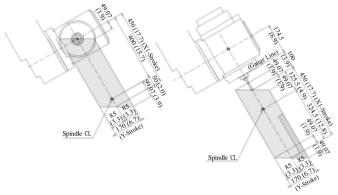


B-axis, Y-axis Working Range

Unit: mm (inch)

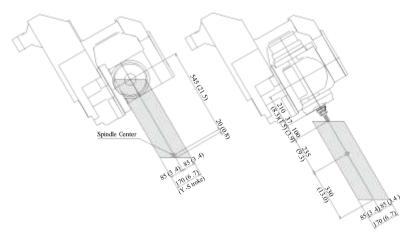
PUMA MX1600

Y-axis working range



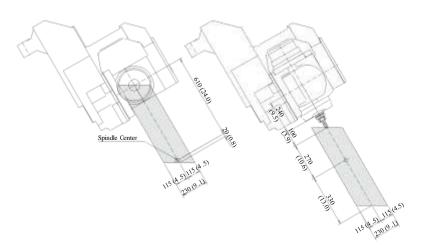
PUMA MX2100

Y-axis working range

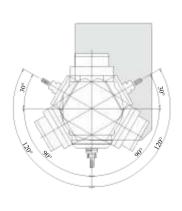


PUMA MX2600 / 3100

Y-axis working range



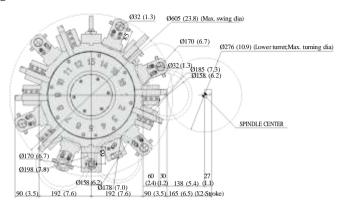
B-axis rotating range



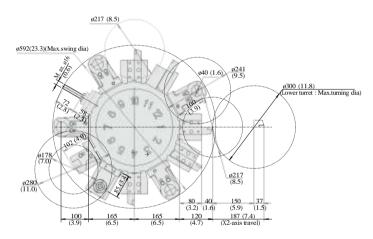
Lower Turret Interference Diagram

Unit: mm (inch)

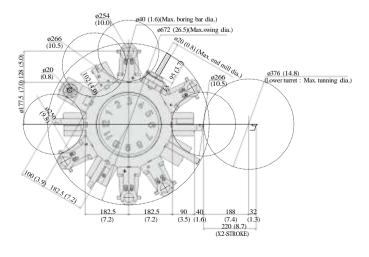
PUMA MX1600



PUMA MX2100



PUMA MX2600



Unit: mm (inch)

PUMA MX1600

970 (38.2) 3300 (129.9)

4746 (186.9)

Top view

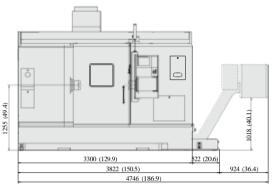
1154 (45.4)

683.5 (26.9)

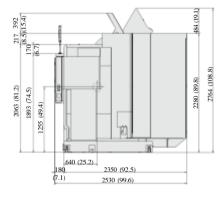
(7.60) 781. (47.74)

1446 (56.9)

Front view

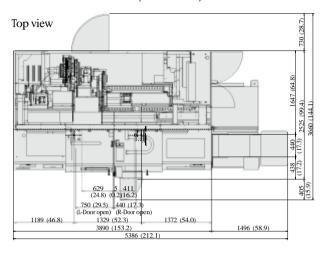


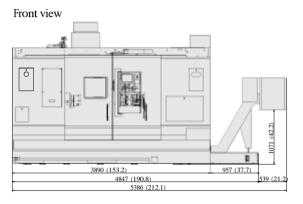
Side view

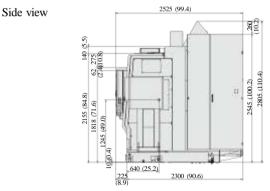


Unit: mm (inch)

PUMA MX2100 (40 Tools)

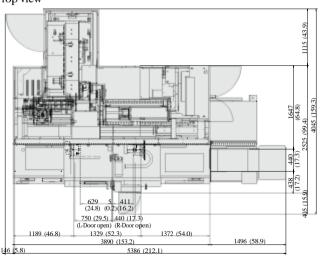




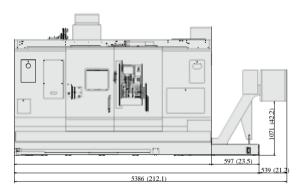


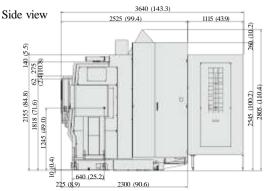
PUMA MX2100 (80 Tools)





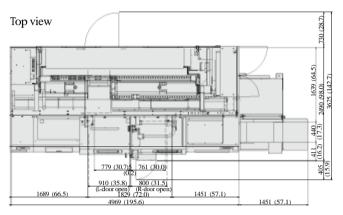
Front view

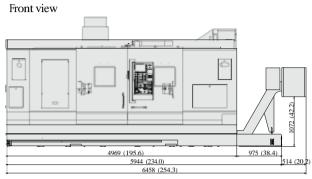




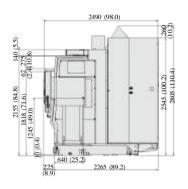
Unit: mm (inch)

PUMA MX2100LST (40 Tools)

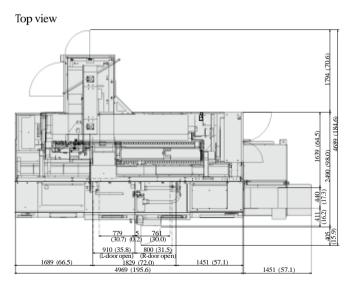




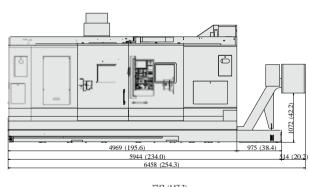
Side view

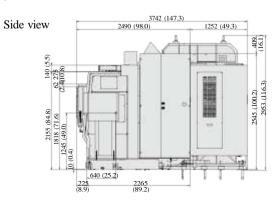


PUMA MX2100LST (80 Tools)



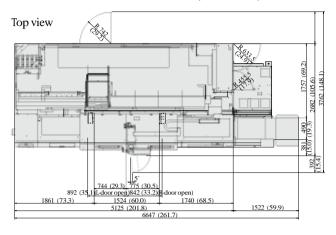
Front view

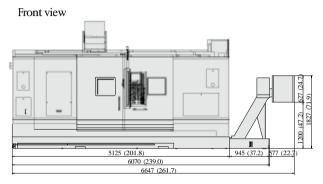




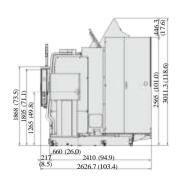
Unit: mm (inch)

PUMA MX2600 / 3100 (40 Tools)

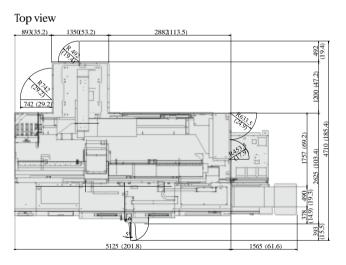


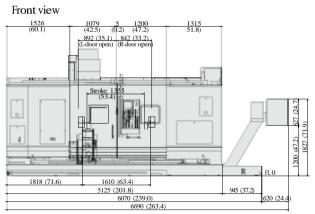


Side view

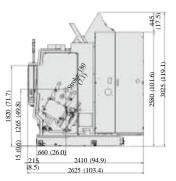


PUMA MX2600 / 3100 (80 Tools)





Side view



Machine Specifications

PUMA MX1600

	Description	Unit	PUMA MX1600	PUMA MX1600S	PUMA MX1600T	PUMA MX1600ST		
	Swing over bed	mm (inch)		680_(26.8)			
	Swing over saddle	mm (inch)		630	24.8)			
	Recom. Turning diameter	mm (inch)		170	(6.7)			
Capacity	Max. Turning diameter	mm (inch)		330 (13.0)			
	Max, Turning length	mm (inch)		900 (
	Chuck size	inch		6	/			
	Bar working diameter	mm (inch)		44 (51) (1	.7 (2.0))			
	X1-axis	mm (inch)		450 (1	. //			
	Z1-axis	mm (inch)		935 (3	,			
	**	mm (inch)		170 (±85) (
Travels	V2 avia	mm (inch)	_	- 170 (1007)		(6.5)		
	distance A2-axis	mm (inch)				(36.4)		
	A-axis	mm (inch)	-	935 (36.8)	923	935 (36.8)		
	A-axis _X1-axis	mm (incn) m/min(ipm)	-	()	17.2)	933 (30.8)		
		\ I /		36 (14	,			
	Rapid Z1-axis	m/min(ipm)	36 (1417.3)					
Feedrates	Traverse Y-axis	m/min(ipm)		26 (10)	23.6)			
reedrates	X7-avie	m/min(ipm)	-	-	24 (944.9)		
	Rate Z2-axis	m/min(ipm)	-	-	36 (1	1417.3)		
	A-axis	m/min(ipm)	-	30 (1181.1)	-	30 (1181.1)		
	Max. Spindle speed	r/min		600	00	30 (110111)		
Spindle nose		ASA		A2-				
Left spindle	Spindle bearing diameter (Front)	mm (inch)	100 (3.9)					
Lett spiritie	Spindle through hole	mm (inch)	62 (2.4)					
	Min. spindle Indexing angle(C-axis			0.00				
				6000	001	6000		
	Max. Spindle speed	r/min	-		-	6000		
	Spindle nose	ASA	-	A2-5	-	A2-5		
Right spindle	Spindle bearing diameter (Front)	mm (inch)	-	100 (3.9)	-	100 (3.9)		
	Spindle through hole	mm (inch)	-	62 (2.4)	-	62 (2.4)		
	Min. spindle Indexing angle(C-axis		-	0.001	-	0.001		
Milling spindle	Max. spindle speed	r/min		120				
wining spindle	Min. spindle Indexing angle(B-axis)	deg.		0.00				
	Tool storage capa. (Max.)	ea		40 {8	RO) Tool			
	changer arm			SWING	ARM			
	Tool selection			FIXED AT	DDRESS			
Automoatic Tool	Max. tool Continous	mm (inch)		70 (2	2.8)			
Changer	diameter Without Adjacent Tool	s mm (inch)		-				
· ·	Max. tool length	mm (inch)		200 (7.9)			
	Max. tool weight	kg (Ib)		4 (8	.8)			
	Tool change time (T-T-T)	s		2.1	· · · · · · · · · · · · · · · · · · ·			
	No. of tool stations	ea	-	_		16		
	OD tool size	mm (inch)		_		(0.8 x 0.8)		
Lower Turret	Max. boring bar size	mm (inch)		_		(1.3)		
Lower runet	Turret Indexing time(1 station swivel).35		
	Max. Rotary tool speed	r/min		_		6000		
	Ouill diameter	mm (inch)	-	-	- 0	000		
T-11 C41-		MT MT	#4	-	- 44	-		
Tail Stock	Quill bore taper			-	#4 -			
	Quill travel	mm (inch)	935 (36.8)	15 / 11 /20	935 (36.8)	-		
	Left spindle motor power	kW (Hp)		15 / 11 (20	.1 / 14.8)	15 (11 (20 1 (11		
Motors	Right spindle motor power	kW (Hp)		15 / 11 (20.1 / 14.8)	-1 (50)	15 / 11 (20.1 / 14.5		
	Milling spindle motor power	kW (Hp)		9 / 3.7 (12				
	Coolant pump motor power	kW (Hp)		2.2 (
Power source	Electric power supply (rated capacity)		43.35	55.28	52.04	-		
	Height	mm (inch)		2760 (1	108.7)			
Machine	Length	mm (inch)		3800 (1	49.6)			
Dimensions	Width	mm (inch)		2530 (99.6)			
	Weight	kg (lb)	11100 (24470.9)	11400 (25132.3)	11300 (24911.9)	11600 (25573.2)		

{ }: Option

Standard Feature

- Tool locating confirmation Spindle thermal
- (Milling Spindle) • Through spindle coolant spindle
- for milling spindle
- Door interlock • Level bolt and plate
- Manual

- Name plate Work light
- - Compensation for milling
 - - Standard tooling kit
 - Foot switch
 - Workpiece cut off Confirmation
 - Signal tower B axis contouring Function (4axes control unit)

Optional Feature

- · Parts unloader and conveyor
- Workpiece ejector
- Rotary type window Wiper
- Linear scale
- Bar feeder interface
- Tool setter
 - Auto. Workpiece Measurement • Automatic front door
- Dual pressure chucking
- Coolant chiller
- · B axis contouring Function (5axes control unit)
- Cooling flow detector
- Steady rest for turret
- Guide bush
- · Hardened & ground jaws • Oil mist collector
- Pressure switch for chucking pressure check
- · Parts unloader and conveyor
- Special chucks

• Oil skimmer

- Through spindle coolant (Left/Right spindle)
- Chip conveyor & bucket
- · Coolant blower
- Tool monitoring System

[•] The specifications and information above-mentioned may be changed without prior notice.

[•] For more details, please contact Doosan.

Machine Specifications

PUMA MX2100

	Description	Unit	PUMA M [L]	PUMA	PUMA	PUMA
			X2100	MX2100S[LS]	MX2100T[LT]	MX2100ST[LST]
	Swing over bed	mm (inch)		750	(29.5)	
	Swing over saddle	mm (inch)		650	(25.6)	
	Recom. Turning diameter	mm (inch)		210	(8.3)	
Capacity	Max. Turning diameter	mm (inch)		540	(21.3)	
	Max. Turning length	mm (inch)		1020 [1520]	(40.2 [59.8])	
	Chuck size	inch			8	
	Bar working diameter	mm (inch)			(2.6)	
	X1-axis	mm (inch)	-		565 (22.2)	
	Z1-axis	mm (inch)	-		1050 [1550] (41.3 [61.0])	
	Travel Y-axis	mm (inch)		170 (±85)	(6.7 (3.3))	
Travels	V2:-	mm (inch)	_	-		(7.4)
	distance Z2-axis	mm (inch)	-	-		(41.3 [61.0])
	A-axis	mm (inch)	_	1050 [1550] (41.3 [61.0])	-	1050 [1550] (41.3 [61
	X1-axis	m/min(ipm)			417.3)	1030 [1330] (11.3 [01
	Z1-axis	m/min(ipm)			417.3)	
	Rapid					
Feedrates	Traverse Y-axis	m/min(ipm)		26 (1	023.6)	
courties	Poto X2-axis	m/min(ipm)	-	<u> </u>		944.9)
	ZZ-axis	m/min(ipm)	_	_	36 (1	417.3)
	A-axis	m/min(ipm)	-	30 (1181.1)	-	30 (1181.1)
	Max. Spindle speed	r/min			000	
	Spindle nose	ASA			2-6	
eft spindle	ndle Spindle bearing diameter (Front) mm (inch) 110 (4.3)		(4.3)			
Spindle through hole		mm (inch)			(3.0)	
	Min. spindle Indexing angle(C-axis	deg		0.0	0001	
	Max. Spindle speed	r/min	_	5000	_	5000
	Spindle nose	ASA	_	A2-6	_	A2-6
Right spindle	Spindle bearing diameter (Front)	mm (inch)	_	110 (4.3)		110 (4.3)
<u> </u>	Spindle through hole	mm (inch)	_	76 (3.0)	_	76 (3.0)
	Min. spindle Indexing angle(C-axis	deg	_	0.001		0.001
· · · · · · · · · · · · · · · · · · ·	Max. spindle_speed	r/min		12	000	
Milling spindle	Min. spindle Indexing angle(B-axis)	deg.		0.0	001	
	Tool storage_capa. (Max.)	ea		40	{80} Tool	
	changer arm			SWIN	IG ARM	
	Tool selection			FIXED A	ADDRESS	
	Tool shank				_	
Automoatic Tool	Max. tool Continous	mm (inch)		90	(3.5)	
Changer	diameter Without Adjacent Tool				(4.7)	
	Max. tool length	kg (Ib)			661.4)	
	Max. tool weight	S ()			9	
	Tool change time (T-T-T)	- S			2.0	
	No. of tool stations	ea	_			2
	OD tool size	mm (inch)	_	<u>_</u>	25 x 25 (1.0 x 1.0)
Lower Turret	Max. boring bar size	mm (inch)	_	_		(1.6)
sower runer	Turret Indexing time(1 station swivel		_	_).2
	Max. Rotary tool speed	r/min				000
	, ,	MT	#4	_	#4	700
Tail Stock	Quill bore taper			-		-
	Quill travel		1050 [1550] (41.3 [61.0])	- 22 /10 5 /	1050 [1550] (41.3 [61.0])	-
	Left spindle motor power	kW (Hp)			(29.5 / 24.8)	22 / 10 5 /20 5 / 24
Motors	Right spindle motor power	kW (Hp)	-	22 / 18.5 (29.5 / 24.8)	40 (201 (110)	22 / 18.5 (29.5 / 24
	Milling spindle motor power	kW (Hp)			4.8 / 20.1 / 14.8)	
	Coolant pump motor power	kW (Hp)			(3.0)	00.500.50
Power source	Electric power supply (rated capacity)		50 [53]	56.7 [75]	50 [53]	88 [89.8]
	Height	mm (inch)			(110.4)	
Machine	Length	mm (inch)			(190.9 [234.1])	
Dimensions	Width	mm (inch)			(99.4 [98.0])	
2111011310113	Weight	kg (Ib)	11500 [12800]	11800 [13800]	11700 [13700]	12000 [14000]

Standard Feature

- Air blast (for chuck)
- Spindle head cooling System
- $\bullet \ \text{Coolant supply equipment} \ \bullet \ \text{Work light}$
- Door interlock • Standard work tools (including holders)
- · Level bolt and plate
- Soft jaws
- Through spindle coolant
- for milling spindle (Milling spindle)
- \bullet Hyd. chuck & actuating cylinder $\,\bullet$ Servo driven tail stock • Hydraulic power unit (except S/ST type machine) Signal tower
- (yellow, red, green)

Optional Feature

- Automatic door with safety device
- Automatic power off
- Tool setter
- Bar feeder
- Bar puller
- Chip Conveyor & Bucket
- Dual chucking pressure
- · Coolant blower
- Hardened & ground jaws
- Oil mist collector
- Oil skimmer
- Pressure switch for chucking pressure check
- · Parts unloader and conveyor
- Special chucks
- Through spindle coolant (Left/Right spindle)
- Work ejector
- Linear scale
- Minimum Quantity Lubrication (MQL) system

 $\{\ \}$: Option

- · Coolant chiller
- Gantry loader
- · Servo driven steady rest (except S/ST type machine)
- Tool monitoring system

- \bullet The specifications and information above-mentioned may be changed without prior notice.
- \bullet For more details, please contact Doosan.

Machine Specifications

PUMA MX2600 / MX3100

	Description	ı	Unit	PUMA MX2600	PUMA MX3100	PUMA MX2600S	PUMA MX3100S	PUMA MX2600T	PUMA MX2600ST
	Swing over b	ed	mm (inch)			1000	(39.4)		
	Swing over s	addle	mm (inch)			700 (27.6)		
	Recom. Turn	ing diameter	mm (inch)	255 (10.0)	310 (12.2)	255 (10.0)	310 (12.2)	255	(10.0)
Capacity	Max. Turning	diameter	mm (inch)			760 (29.9)		
• •	Max. Turning	length	mm (inch)			1540	(60,6)		
	Chuck size	,	inch	10	12	10	12		10
	Bar working	diameter	mm (inch)	76 (3.0)	102 (4.0)	76 (3.0)	102 (4.0)		(3.0)
	Dai working	X1-axis	mm (inch)	70 (3.0)	102 (4.0)	630 (70	(3.0)
		Z1-axis	mm (inch)				(62.4)		
		Y-axis	mm (inch)				(9.1 (4.5))		
Travels	Travel						(9.1 (4.3))	220	(0.7)
	distance	X2-axis	mm (inch)	-	-	-	-		(8.7)
		Z2-axis	mm (inch)	-	-	- 1550	- (51.0)		(59.6)
		A-axis	mm (inch)	-	-	1550		-	1550 (61.0
		X1-axis	m/min(ipm)			36 (14			
		Z1-axis	m/min(ipm)			36 (14	117.3)		
	Rapid	Y-axis	m/min(ipm)			26 (10)23.6)		
Feedrates	Traverse	X2-axis	m/min(ipm)			20 (1)	(23.0)	24 ((944.9)
	Rate	72-axis		-	_	-	_		417.3)
			m/min(ipm)	-	-	20.41	01.1)	30 (1	
		A-axis	m/min(ipm)	1000	2000	30 (11		-	30 (1181.1
	Max. Spindle		r/min	4000	3000	4000	3000		000
	Spindle nose		ASA	A2-8	A2-11	A2-8	A2-11		2-8
Left spindle		ing diameter (Front)	mm (inch)	130 (5.1)	160 (6.3)	130 (5.1)	160 (6.3)		(5.1)
	Spindle thro	ugh hole	mm (inch)	86 (3.4)	115 (4.5)	86 (3.4)	115 (4.5)	86	(3.4)
	Min. spindle Indexing angle(C-axis)		deg			0.0	001		
	Max. Spindle	speed	r/min		_	40	00	_	4000
	Spindle nose		ASA	_	_	A.	2-8 -		A2-8
Right spindle	Spindle bearing diameter (Front)		mm (inch)	_	_	130	(5.1) -		130 (5.1
ragin spinare	Spindle through hole		mm (inch)	_	_	86 (()	_	86 (3.4
		Indexing angle(C-axis)				0.0			0.001
	Max. spindle		r/min		-		000	-	0.001
Milling spindle									
		Indexing angle(B-axis)	deg.			0.0			
		capa. (Max.)	ea				80) Tool		
	_changer_arm						G ARM		
	Tool selection					FIXED A			
Automoatic Tool	Max. tool	Continous	mm (inch)			90 (3.5)		
Changer	diameter	Without Adjacent Tools	mm (inch)			130	(5.1)		
	Max. tool ler	igth	kg (Ib)			400 (8	381.8)		
	Max. tool we	eight	S			1	0		
	Tool change		s			2	.0		
	No. of tool st		ea	-	_	_			12
	OD tool size		mm (inch)		_	_	_		1.0 x 1.0)
Lower Turret	Max. boring	har size	mm (inch)	_	_	_	_		(1.6)
Lower rullet		ng time(1 station swivel)	S S						1.2
			r/min	-	-	_			000
	Max. Rotary			-	-	-		40	00
Tail Stock	Quill bore tap	per	MT	#.		-	#5	-	-
Stock	Quill travel		mm (inch)	1550		-	1550 (61.0)	-	
	I oft a!	manton morrio:	LW (II.	26 / 22	30 / 25	26 / 22	30 / 25		/ 22
	Left spindle	motor power	kW (Hp)	(34.9 / 29.5)	(40.2 / 33.5)	(34.9 / 29.5)	(40.2 / 33.5)	(34.9	(29.5)
				(51.7 / 27.5)		26	/22		26 /22
Motors	Right spindle	motor power	kW (Hp)		_			_	26 / 22
		•					/ 29.5)		(34.9 / 29.5
		le motor power	kW (Hp)		2		9.5 / 24.8 / 20.1)	
	Coolant pum	p motor power	kW (Hp)			2.2	(3.0)		
Power source	Electric power	r supply (rated capacity)	kVA	70	80	90	100	70	100
	Height	1 0/	mm (inch)			3025 (119.1)		
Machine	Length		mm (inch)			5125 (
Dimensions	Width		mm (inch)			2625 (
Difficultion	Weight		kg (Ib)		14600 (32187.0)			L	

{ } : Option

Standard Feature

- Air blast
- Spindle head cooling system
- Coolant chiller • Door interlock
- Work light
- Standard work tools
- Through spindle coolant for milling spindle
- (including holders)
- Servo driven tail stock • Hyd. chuck & actuating cylinder (except S/ST type machine)
- Hydraulic power unit * Severabolt and plate
- Signal tower (yellow, red, green)

- Automatic door with safety device

Optional Feature

- Automatic power off • Tool setter
- Bar feeder
- Bar puller
- Chip Conveyor & Bucket * Goalantublangrpressure
- Hardened & ground jaws
- Oil mist collector Oil skimmer
- Pressure switch for chucking pressure check
- Parts unloader and conveyor
- Special chucks • Through spindle coolant
- Work ejector
- Linear scale
- Minimum Quantity Lubrication (MQL) system
- Coolant Chiller
- Gantry loader
- Servo driven steady rest
- (Texasphotal Stitus synaghine)

[•] The specifications and information above-mentioned may be changed without prior notice.

[•] For more details, please contact Doosan.

NC Unit Specifications

Fanuc 31i

	1 path / 2
path	X1, Z1, C1, Y, B, A, X2, Z2,
- Controlled axes	X1, Z1, C1, Y, B, A, X2, Z2,
C2	
- Simultaneous controlle	
4 (5-On B5)axes	lly for Fanuc 31i-A5 /
Amoulou ovio control	
Racklach companeat	tion $0 \sim \pm 9999$ pulses
- Backlasii compensat	non 0 - ±//// puises
- Backlash compensatio	on for each rapid traverse
and cutting feed	m ror outer rupid daverse
- Chamfering on/off	
- Synchronous / Comp	posite control
- Superimposed Contr	rol
- HRV2 control	
- Inch / Metric conver	rsion
	All axis / each
axis	
- Least input comman	d 0.001 / 0.000 1
Mashina lastr	All axis / each
- Machine lock	All axis / each
axis - Mirror image	
- Position switch	
- Servo off	
- Stored pitch error cor	npensation
- Stored stroke check	1
- Torque control	
- Interference chek for	r rotary area
- Unexpected disturba	ince torque detection
function	
OPERATION	
- DNC Operation with	Memory card
- Buffer register	
- Dry run	feed X1, X10, X100
 Handle incremental 	feed X1, X10, X100
- Program restart	
- Wrong operation pre	evention
- JOG feed	
- Manual pulse genera	ator (Portable MPG) 1 ea
	osition return
- Single block	
 Tool direction handle 	e feed (G68.1)
INTERDOLATION FOR	NOTIONS
INTERPOLATION FUL	NCTIONS
- Nano interpolation	
- 1st. Reference positi	ion return Manual, G28
2.1.6	
	ion return G30
- 3rd/4th reference po	osition return
 3rd/4th reference po AICC (Number of loc 	osition return okhead block : 30 Blocks)
- 3rd/4th reference por - AICC (Number of loc - Balance cutting (Onl	osition return okhead block : 30 Blocks) ly for 2 path)
3rd/4th reference poAICC (Number of locBalance cutting (OnlContinuous threadin	osition return okhead block : 30 Blocks) ly for 2 path) g
 3rd/4th reference per AICC (Number of loc Balance cutting (Onl Continuous threadin Cylindrical interpolat 	osition return okhead block : 30 Blocks) ly for 2 path) g ion
 3rd/4th reference per AICC (Number of loc Balance cutting (Onl Continuous threadin Cylindrical interpolat Dwell (per sec.) 	osition return okhead block : 30 Blocks) ly for 2 path) g ion
3rd/4th reference per AICC (Number of loc Balance cutting (Onl Continuous threadin Cylindrical interpolat Dwell (per sec.) Multiple threading	osition return okhead block: 30 Blocks) y for 2 path) g ion G04
3rd/4th reference per AICC (Number of loc Balance cutting (Onl Continuous threadin Cylindrical interpolated Dwell (per sec.) Multiple threading Polar coordinate interpolated Dwell (per sec.)	osition return okhead block: 30 Blocks) by for 2 path) g ion G04 erpolation
- 3rd/4th reference pc - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position r	osition return khead block: 30 Blocks) y for 2 path) g ion G04 erpolation eturn check G27
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining	osition return skhead block: 30 Blocks) ly for 2 path) g ion G04 erpolation eturn check with two spindle
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining versions	osition return skhead block: 30 Blocks) ly for 2 path) g ion G04 erpolation eturn check with two spindle G31
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining versions of the coordinate interpolation of the coordinate inte	osition return okhead block: 30 Blocks) by for 2 path) g ion G04 erpolation eturn check with two spindle G31 achronous cutting
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining versions	osition return okhead block: 30 Blocks) by for 2 path) g ion G04 erpolation eturn check with two spindle G31 achronous cutting
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position r - Polygon machining v - Skip - Thread cutting / Syr - Torque limit skip	osition return okhead block: 30 Blocks) by for 2 path) g ion G04 erpolation eturn check with two spindle G31 achronous cutting
- 3rd/4th reference pc - AICC (Number of loc - Balance cutting (Onl - Boundary of the Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining v - Skip - Thread cutting / Syr - Torque limit skip FEED FUNCTION	osition return whead block: 30 Blocks) by for 2 path) g ion G04 expolation eturn check with two spindle G31 achronous cutting
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining very - Skip - Thread cutting / Syr - Torque limit skip FEED FUNCTION - Automatic accelerating	osition return khead block: 30 Blocks) y for 2 path) g ion G04 erpolation eturn check with two spindle achronous cutting on / deceleration
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining v - Skip - Thread cutting / Syr - Torque limit skip - Automatic accelerati - Cutting feedrate clar	osition return khead block: 30 Blocks) y for 2 path) g ion G04 erpolation eturn check with two spindle achronous cutting on / deceleration
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining v - Skip - Thread cutting / Syr - Torque limit skip - FEED FUNCTION - Automatic accelerati - Cutting feedrate clar - Feed per minute	osition return whead block: 30 Blocks) ly for 2 path) g ion G04 erpolation eturn check G27 with two spindle hechronous cutting on / deceleration mp
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position r - Polygon machining - Skip - Thread cutting / Syr - Torque limit skip - Torque limit skip - FEED FUNCTION - Automatic accelerati - Cutting feedrate clar - Feed per minute - Feed per revolution	osition return whead block: 30 Blocks) ly for 2 path) g ion G04 erpolation eturn check G27 with two spindle achronous cutting G01 G01 G031
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining v - Skip - Thread cutting / Syr - Torque limit skip - FEED FUNCTION - Automatic accelerati - Cutting feedrate clar - Feed per minute	osition return whead block: 30 Blocks) ly for 2 path) g ion G04 erpolation eturn check G27 with two spindle achronous cutting G01 G01 G031
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining v - Skip - Thread cutting / Syr - Torque limit skip FEED FUNCTION - Automatic accelerati - Cutting feedrate clar - Feed per minute - Feed per revolution - Feedrate override (1)	osition return khead block: 30 Blocks) y for 2 path) g ion G04 erpolation eturn check with two spindle achronous cutting G31 on / deceleration mp 0% unit) 0 - 200 %
- 3rd/4th reference pe - AICC (Number of lot - Balance cutting (Onl - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position r - Polygon machining v - Skip - Thread cutting / Syr - Torque limit skip - Thread cutting / Syr - Torque limit skip - Cutting feedrate clar - Feed per minute - Feed per minute - Feed per revolution - Feedrate override (19)	osition return okhead block: 30 Blocks) ly for 2 path) g lion G04 erpolation eturn check G27 with two spindle G31 achronous cutting G31 on / deceleration mp
- 3rd/4th reference pe - AICC (Number of loc - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position re - Polygon machining very - Skip - Thread cutting / Syr - Torque limit skip - Torque limit skip - FEED FUNCTION - Automatic acceleratic - Cutting feedrate clar - Feed per minute - Feed per revolution - Feedrate override (1) - Jog feed override (1) - Manual per revolution	osition return okhead block: 30 Blocks) ly for 2 path) g lion G04 erpolation eturn check G27 with two spindle G31 achronous cutting G31 on / deceleration mp
- 3rd/4th reference pe - AICC (Number of lot - Balance cutting (Onl - Balance cutting (Onl - Continuous threadin - Cylindrical interpolat - Dwell (per sec.) - Multiple threading - Polar coordinate inte - Reference position r - Polygon machining v - Skip - Thread cutting / Syr - Torque limit skip - Thread cutting / Syr - Torque limit skip - Cutting feedrate clar - Feed per minute - Feed per minute - Feed per revolution - Feedrate override (19)	osition return khead block: 30 Blocks) y for 2 path) g ion G04 erpolation eturn check with two spindle achronous cutting G31 achronous cutting 0% unit) 0 - 200 % 0% unit) 0 - 200 mm/min. on feed

PROGRAM INPUT - 3D coordinate conversion	
Addition of custom macro commo	
	199, #500~#999
- Canned cycle for turning	
- Circular interpolation by R prog	gramming
- Coordinate system setting	G50
- Coordinate system shift	
- Custom macro	
- Decimal point programming	ar .
- Diameter/radius programming (
 Direct drawing dimension progr Direct input of coordinate system 	ramming
	em smit
- Input unit 10 time multiply	
- Label skip	
- Macro executor	
- Manual absolute on and off	
- Maximum program dimension - Multiple repetitive canned cycle	±9 digit
 Multiple repetitive canned cycle 	e G70 - G76
- Multiple repetitive canned cycle	
- Optional block skip - Plane selection	G17 G18 G10
- Flatic Sciection	
- Program file name	
- Programmable data input	G10
- Sequence number	N8 digit
- SUB program call	10 folds nested
Tomo ando - ISO / EIA auto magazi	ition
-Tape code : ISO / EIA auto recogni	IA RS422/ISO840
H	11 10722/100070
E	
	5
- Tape format for FANUC Series1	.5 G52 - G59
- Tape format for FANUC Series1	.5 G52 - G59
- Tape format for FANUC Series1 - Work coordinate system	G52 - G59
- Tape format for FANUC Series1 - Work coordinate system	G52 - G59
- Tape format for FANUC Series1 - Work coordinate system TOOL FUNCTION / TOOL CO - Automatic tool offset	G52 - G59 MPENSATION
- Tape format for FANUC Series 1 - Work coordinate system TOOL FUNCTION / TOOL COI - Automatic tool offset - Direct input of offset value me	MPENSATION casured
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL COI - Automatic tool offset - Direct input of offset value me - Direct input of offset value me	MPENSATION easured easured B
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL COI - Automatic tool offset - Direct input of offset value me - Direct input of offset value me	MPENSATION easured easured B
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL COI - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function	MPENSATION easured T2 + 3 digits
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL COI - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function - Tool geometry / wear compens	G52 - G59 MPENSATION easured B T2 + 3 digits sation
- Tape format for FANUC Series 1 - Work coordinate system TOOL FUNCTION / TOOL COI - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function - Tool geometry / wear compens	G52 - G59 MPENSATION easured B T2 + 3 digits sation
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL CO - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function Tool geometry / wear compens - Tool life management - Tool nose radius compensation	MPENSATION casured casured B T2 + 3 digits
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL CO - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function Tool geometry / wear compens - Tool life management - Tool nose radius compensation	MPENSATION casured casured B T2 + 3 digits
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL COI - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function Tool geometry / wear compens - Tool life management - Tool nose radius compensation	MPENSATION casured casured B T2 + 3 digits
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL CO - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function Tool geometry / wear compens - Tool life management - Tool nose radius compensation	MPENSATION casured casured B T2 + 3 digits
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL CO - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function - Tool geometry / wear compens - Tool life management - Tool onse radius compensatior - Tool offset - Tool offset pairs Upper: ±6 Lower:	G52 - G59 MPENSATION casured B T2 + 3 digits sation 1 G43, G44, G49 digits : 400 pairs ±6 digits : 99
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL CO - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function - Tool geometry / wear compens - Tool life management - Tool onse radius compensatior - Tool offset - Tool offset pairs Upper: ±6 Lower:	G52 - G59 MPENSATION casured B T2 + 3 digits sation 1 G43, G44, G49 digits : 400 pairs ±6 digits : 99
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL CO - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function - Tool geometry / wear compens - Tool life management - Tool offset - Tool offset - Tool offset pairs - Tool offset pairs - Upper: ±6 - Lower: - Lower: - Lower: - Lower input - Lower input	G52 - G59 MPENSATION casured B T2 + 3 digits sation 1 G43, G44, G49 digits : 400 pairs ±6 digits : 99
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL CO - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function - Tool geometry / wear compens - Tool life management - Tool offset - Tool offset - Tool offset pairs - Tool offset pairs - Upper: ±6 - Lower: - Lower: - Lower: - Lower input - Lower input	G52 - G59 MPENSATION casured B T2 + 3 digits sation 1 G43, G44, G49 digits : 400 pairs ±6 digits : 99
- Tape format for FANUC Series I - Work coordinate system TOOL FUNCTION / TOOL COI - Automatic tool offset - Direct input of offset value me - Direct input of offset value me - T - code function - Tool geometry / wear compens - Tool life management - Tool onse radius compensatior - Tool offset - Tool offset pairs - Upper: ±6 - Lower: airs - Tool offset value counter input - Y-axis offset	G52 - G59 MPENSATION casured B T2 + 3 digits sation 1 G43, G44, G49 digits : 400 pairs ±6 digits : 99
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(Note) Specify total of part program storage size of each

Cycle start and lamp Display unit Feed hold and lamp MDI unit for NC and servo ready PMC system PMC-31ii Reset / rewind INTERFACE FUNCTION Embedded etherne	D A
Feed hold and lamp	D A
- MDI unit for 10.4" LCI - NC and servo ready - PMC system PMC-31i# - Reset / rewind	Α
NC and servo ready PMC system Reset / rewind INTERFACE FUNCTION	Α
Reset / rewind	_
INTERFACE FUNCTION	
INTERFACE FUNCTION Ethernet function Embedded ethernet	
Ethernet function Embedded etherne	Ƞ
	/L
OPERATION	
- DNC operation (Reader/puncher interface is requi	ired)
Reference position shift	
•	
OPERATION GUIDANCE FUNCTION	_
EZ Guide-i (Conversational Programming Solution	on)
TOOL FUNCTION / TOOL COMPENSATION	
- Tool monitoring system	
PTIONAL SPECIFICATIONS	
INTERPOLATION FUNCTIONS	_
INTERPOLATION FUNCTIONS Circular threading	<u>-</u>
INTERPOLATION FUNCTIONS Circular threading Multi step skip	
INTERPOLATION FUNCTIONS Circular threading Multi step skip Variable lead threading	
INTERPOLATION FUNCTIONS Circular threading Multi step skip	
INTERPOLATION FUNCTIONS Circular threading Multi step skip Variable lead threading High speed skip FEED FUNCTION	_
INTERPOLATION FUNCTIONS Circular threading Multi step skip Variable lead threading High speed skip FEED FUNCTION Al Contour control (Look-ahead block no. is MAX.200)	_
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INTERPOLATION FUNCTIONS Circular threading Multi step skip Variable lead threading High speed skip FEED FUNCTION Al Contour control (Look-ahead block no. is MAX.200)	_
INTERPOLATION FUNCTIONS - Circular threading - Multi step skip - Variable lead threading - High speed skip FEED FUNCTION - Al Contour control (Look-ahead block no. is MAX.200) - External deceleration - Feed stop	_
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INTERPOLATION FUNCTIONS - Circular threading - Multi step skip - Variable lead threading - High speed skip FEED FUNCTION - Al Contour control (Look-ahead block no. is MAX.200) (- External deceleration - Feed stop OPERATION - Manual handle interruption	35.1 —
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INTERPOLATION FUNCTIONS - Circular threading - Multi step skip - Variable lead threading - High speed skip FEED FUNCTION - Al Contour control (Look-ahead block no. is MAX.200) (- External deceleration - Feed stop OPERATION - Manual handle interruption - Tool retract and recover	35.1
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(Includs software operators panel)

path - Memory card program edit & operation - Program protect		
SETTING AND DISPLAY - Actual cutting feedrate display - Alarm history display - Periodic maintenance screen - Display of spindle speed and T code at all screens - Optional path name display (Only for 2path) - Multi-language display - Operation history display	EDITING OPERATION - Part program storage size 1MB / 2MB - Play back SETTING AND DISPLAY - Directory display of floppy cassette	_
- Run hours / part count display - Self-diagnosis function - Spindle orientation - Constant surface speed control	DATA INPUT/OUTPUT - Data server - M-code function - Multi spindle control	M3 digits

NC Unit Specifications

S4 / S5 digits - Spindle speed override 0 - 150 %

- Spindle synchronous control - Actual spindle speed output

- Servo setting screen
- Spindle setting screen

DATA INPUT/OUTPUT

- External key input - External data input 15 points - External work number search

- Memory card input/output Reader/puncher interface CH1.ir - RS232C interface - Automatic data backup (자동 데이터 백업) CH1.interface

- Screen hard copy

- DNC control

CONTOURING FUNCTION

- Tool center point control by 5-axes: just on FANUC 31i-A5 / B5 - High Speed machining (600 blocks)

ROBOT INTERFACE

- Robot interface with PMC I/O module (Hardware between PMC I/O mudules)

- Robot interface with PROFIBUS-DP

• Soft jaws • Dual chucking pressure

• The specifications and information above-mentioned may be changed without prior notice. • For more details, please contact Doosan.

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(Left/Right spindle)

• Tool monitoring system





http://www.doosaninfracore.com/machinetools/

Doosan Infracore Machine Tools

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⁻ For more details, please contact Doosan.

